

D5.1 Case study involving an urban area with a transportation node, as well as the sub-urban areas, the semi-periphery and rural areas connected to this transportation node

Status	
Authors	Alan Berger, Karl Otto Ellefsen, Espen Aukrust Hauglin (AHO)
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A STUDY OF POSSIBLE ADAPTIONS AND SPATIAL IMPACTS OF AV TECHNOLOGIES IN THE MUNICIPALITY OF SKI, OSLO METROPOLITAN AREA

Future urbanism: Planning for Autonomous Vehicles (PAV). Institute of Urbanism and Landscape Oslo School of Architecture and Design

The Elective Course Future urbanism: Planning for Autonomous Vehicles is a part of ongoing invention and research processes concerning automatic vehicles (AV). New hybrid transport systems will in the years to come influence settlement structure, habitat and urban design. The course links to the networks of the European research project PAV (Planning for autonomous vehicles) investigating challenges related to urban planning and design, and its possible spatial impacts.

Teachers

Assistant professor Espen Aukrust Hauglin (coordinator) Professor Alan Berger, MIT Professor Karl Otto Ellefsen, AHO

Students

Deheng Kong, Oscar Frank, Johannes Hecker, Noah von Stietencron, Philipp Wadehn

The course is linked to the work on autonomous vehicles conducted by Ruter, the public transport authority for the Oslo metropolitan area.

Ruter experts

Ola Skar, Director of transportation and land-use planning, Lars Gunnar Lundestad, Project manager

Ruter has been working with different pilot-projects to test out the use of self-driving vehicles. In 2021 a major pilot-project is localized to Ski in Nordre Follo Municipality, linking the Hebekk area – a low density housing-area – to Ski station. The intention of the pilot is to gain empirical data in order to answer technical and functional questions. Ruter tests out "the most proven technology in the marked", in the Ski pilot adapted to standard Toyota mini-buses, Toyota Proace, with technology from Sensible 4.

The pilot in Ski is especially intended to create new knowledge on:

- Higher speed stabile, seamless operation within a 50 km per hour zone (with existing traffic.)
- Weather conditions ability to tackle Nordic weather conditions in all parts of the year. Snow is a particular challenge.
- On-demand functionality development of systems for handling on-demand.
- Autonomous, non-manned operation.



The "Ski Learning Goals", defined and elaborated by Ruter

Presented by Lars Gunnar Lundestad

https://ahocloud.box.com/s/8r01hjkxv3o1jt14wti3p3pqgxn6k2cb

Stable, seamless operation in 50-zone

- Behaviour and perceived safety in higher speed
- Traffic cooperation in normal traffic conditions.

Validation of Oslo mobility study

- Ride sharing in smaller vehicles
- Integration with high-capacity transport network

Integration with infrastructure

- V2X communication with infrastructure (e.g. automatic gate)
- V2X integration with temporary traffic lights (e.g. during construction work)

Dynamic routing

- Dynamic routing based on customer needs
- Point to point mobility
- Dynamic routing based on roadworks and construction.

Fleet of different vehicles

- Potential for POC-test with vehicles of various size and types
- Test of Kiss & Drive in relation to public transport HUB's

Regulating departure times and management for holding areas

Unmanned operation

- Potential for operator outside vehicle



AHO study – APPROACH

- In this study, the Ski pilot is discussed as a possible model for a new local transportation system in the municipality of Nordre Follo. The settlement pattern of the municipality is rather typical for the peri-urban parts of the metropolitan area, therefore the study has a general relevance.
- Referring to the literature list being developed as part of the AHO-project by Alan Berger (MIT), the possible future for the adaption of AV technology – options/potentials/consequences – are rather open. The AHO study is limited to a discussion of adaptions in the near future:
- A system of AV lines supporting the area, based on a time-schedule (mini-buses).
- These lines operating On-demand.
- A possible future where AV is fully adapted to a revised
- Road-system and may "go everywhere" is not taken into account in this preliminary study.

The AHO study is divided into two parts:

Discussing the model for AV used in the pilot, and testing it out for adaption on four levels:

- The Municipality of Nordre Follo
- Ski town
- The Hebekk area
- Ski station area.

Discussing the potentials for adaption and transformation in the Hebekk area, created by an alternative AV transportation system.





The municipality of Nordre Follo

The municipality of Nordre Follo in Viken County is located south of Oslo and borders the Oslofjord (Bunnefjorden) to the west and Østmarka (a protected forested recreational area) and the municipality of Enebakk to the east and southeast. The administrative centre is the town of Ski. With a distance of about 20 kilometers, the town may – after completion of a new tunnel (2022) – be reached in about 15–20 minutes by train from Oslo Central station.

Nordre Follo hosts a population of 59.288 inhabitants. The density is relatively low and accounts for 306,3 inhabitants per square kilometer due to abundant green-structure and low-density housing typology, single-family housing accounting for around 70 percent of the total. With regard to the subject of the study, one might note that there are 15,845 residential buildings within the municipality, and almost as many garage buildings (13,387). With a population of around 60,000 inhabitants, it may be assumed that each family has at least one car at its disposal.

The main traffic artery of Nordre Follo is the railroad line Østfoldbanen, leading from Oslo to Ski and further to Sweden. The most populated settlements in the municipality are located along this line, as is the situation with Kolbotn and Ski. At Ski the railroad is divided into two lines, one via Krågstad to Skotbu (Inner Østfold line) and one serving the cities along the coast.

A total of 10 stations on the 24-kilometer-long railroad line constitute the traffic hubs of the municipality. Starting from these points, the presentation maps the residential areas at walkingdistances of 500 and 1000 meters. For the population, a distance radius of more than 1000 meters often means the need for their own car or an available bus connection. Districts that fall into this category are both more rural settlements, such as Siggerud with 969 inhabitants, and urban districts with a longer distance to the station, such as Kontra with 824 inhabitants.

The presentation then marks the transformation areas planned by the municipality. Some are localized at relatively short distances from train-stops (Myrvoll, Vevelstad, Langhus and Ski). Areas around the municipalities of Vevelstad and Langhus are also localized within a radius of 1000m from the transportation hub. Outlying transformation areas with a distance of more than one kilometer are found east of Ski, northeast of Vevelstad and in the northwest of the municipality.

The following pages of the presentation map the specific transformation areas and the housing areas previously discussed. Both types of areas are presented graphically at a distance from the traffic junction of less than 1000m and at a distance from the traffic junction of more than 1000m.

Finally, the last page of the first section of our presentation maps all the residential and transformational areas of the municipality. Graphically highlighted are development areas that – with existing infrastructure, existing user groups, and large-scale transformation areas provided by the municipality – offer very good potential for AV transportation.













> service through bus connections

Nordre Follo

Municipality level





Nordre Follo

Municipality level





Development areas outside the transportation nodes

Housing areas

> 1000m distance

Transformation areas

> 1000m distance

Nordre Follo

Municipality level





The level of Place



The urban area of Ski is discussed as a localization for AV, based on the model of the Ruter Pilot. Areas are categorized according to their characteristics and their localization. A system of possible AV routes servicing the area is proposed. While the Ruter Pilot follows a loop, the proposed system is based on lines transecting the Ski urban area.

The area for micro mobility

The extent of the micro mobility area in the center of Ski will vary according to the main types of transportation used. It is important to take into account the impact of electric scooters, bikes and other vehicles. Even though the distance radiuses in the presentation are displayed as concentric circles around the train station, they do not necessarily represent real distances. Actual routes from the transportation hub to individual homes or other places differ from the linear distance based on the road layout. This has to be considered when actually defining the micro mobility area.

Established residential areas

Ski is divided into two large residential areas, one to the West and one to the East of the train line. Each of these can be split up into two smaller areas. The current autonomous bus pilot drives along a loop line, having several stops on the border of the area that is to be served. Areas in the municipality with lower centrality

There are currently four smaller remote residential areas around Ski. One to the West next to the E18, one to the south in direction of Kråkstad and two north of Ski. The latter might at some point merge with the north-eastern residential area, but at present it is possible to clearly distinguish the four remote areas from the inner zone. It seems valuable to place future autonomous bus stops close to the four remote areas. Even without stops directly in the area, this could reduce the walking distance and serve parts of the remote areas. In the future these areas could benefit from on-demand autonomous vehicles that are not line based.



Development areas

The development areas – mainly the one south of the western residential area and one to the very east of Ski – hold great potential in terms of autonomous vehicle planning. To increase the benefits and impact of autonomous transportation it is necessary that Ruter is closely involved in the city planning processes as early as possible. Developments and findings from the pilot project must be continuously integrated into the planning process. Proposal for AV lines

The three proposed AV lines take the individually addressed aspects into account and apply the straight line concept. This is beneficial for public transport users as they do not have to travel unnecessary distances when living at an unfavourable end of the loop. One of the proposed lines covers the western part of Ski while a second one serves the East. A third line transect the urban area from the eastern to the western end. All three lines stop at the transportation hub in the center of Ski. The proposed lines have the potential to not only serve the development areas but also the four remote areas by stopping close by or entering them. Monodirectional AVs could make use of some the many roundabouts in Ski to turn around at the end of their routes.





















































Straight line concept

Possible future line

The Level of Place















AV PUDO and road system around Ski station

We have conducted a field research around Ski station and come up with a few scenarios to show future traffic possibilities around Ski station. Our proposed scenarios do not represent 1 to 1 scale and should not be treated as so. Instead they are meant to create discussion and thought for future planning of Ski station.





Source: <u>www.aftenposten.</u> Date: 21st of August 2020





























Potentials for Transformation

Parts of the area of Hebekk in Ski was studied in order investigate the potentials for revised use of areas, development of green structure and eventual densification

The first three illustrations shows comparable studies from the US (Alan Berger) and work as a model for discussing the future structure and morphology of Hebekk.





BEACON PARK NEW TYPOLOCY	MORE BASED ON MORE-CATENT OF THIS ORE UNIT
DENSITY 98 homes, 10.37 acres 9.45 homes/acre	
HOUSING 2526 sq ft GFA	
BUILT-UP 0.55 FAR AREA 0.27 COV	non nors
NON-BUILT UP AREA impervious : pervious 49% : 51 % 44% reduction in impervious surfaces	
OPEN SPACE OF DIFFERENT SIZES ALLOW FOR A	
VEHICULAR ACCESS BERNID THE HOMES SIGARD FICK UP/ DRON-ON-HORTS	
PEDESTRIAN VEHICUL MOBILITY MOBILIT	R PRATE PUBLIC V OPEN SPACES OPEN SPACES (33% of pervious) (40% of pervious)













11342

Build ngs

Main driveway

Car path

https://www.ssbino/familie/

Walk path

Deheng Kong & Oscar Frank

Upper Myrsletta

During the first assignment we considered to work further with the left side of our our area for assignment 2, but after discussion and further consideration we decided to work with the northern part of our total area called Myrsletta, this section proposed more potential, to better understand the possibilities of AV.

Metrics

Total site area: 39661 m² Impervious area: 15336 m² (38,6% of total area) Pervious area: 24325 m² Pervious to impervious ratio: 1/0.63

Examination





Road

Garage parking

Upper Myrsletta New Typology

We propose to change the road system for AV of Myrsletta as seen on this page. The position of the houses are unchanged. The parking areas are gone and have freed up space to create public recreational areas to increase quality of life and amount of pervicus area around Myrsletta.

Metrics

Total site area: 39661m2 Impervious area: 7424m2 18,7 % impervious of total site area 51,5% decrease in current impervious area

Examination





Road

Public Areas





